

# Panasonic

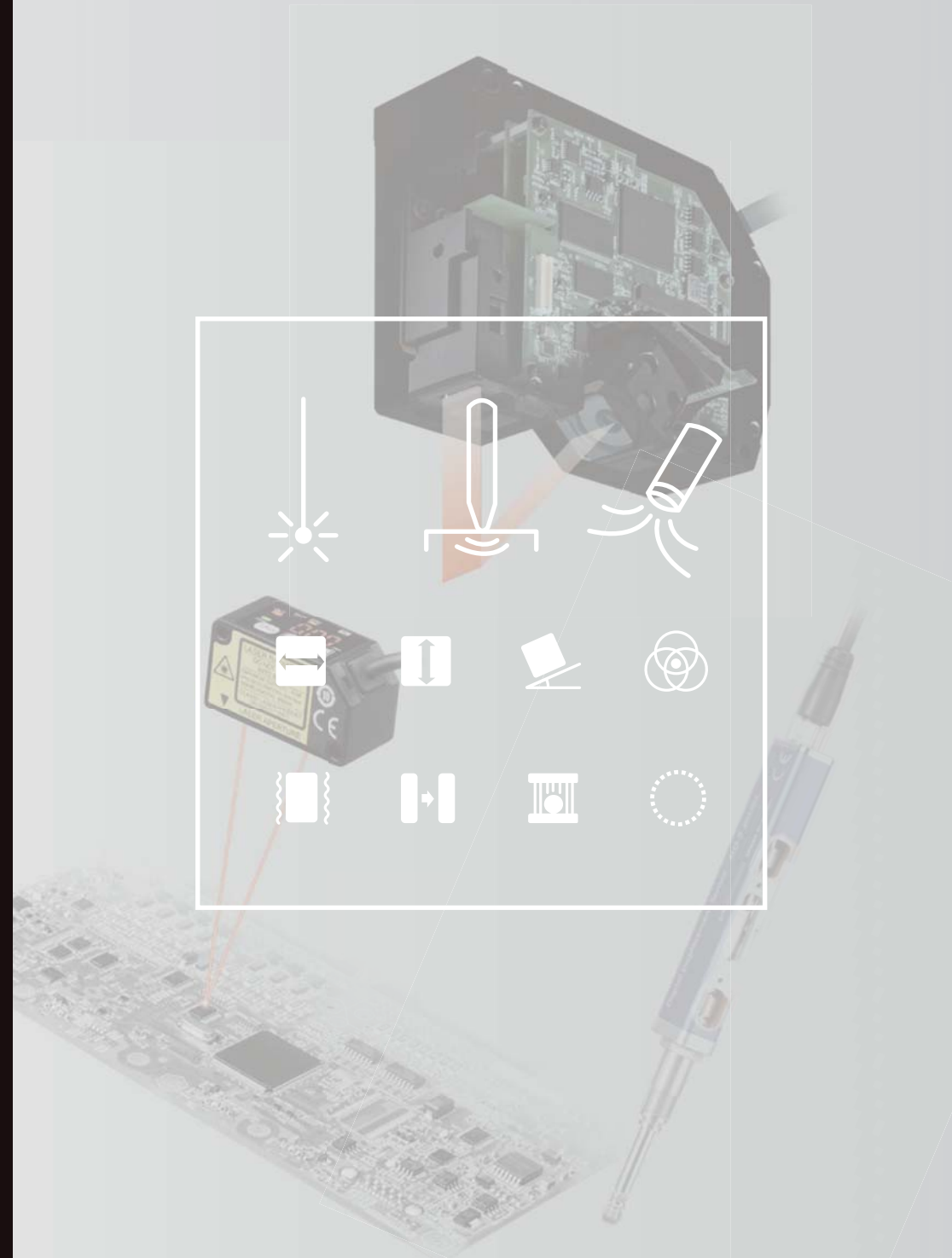
Overview

## Measurement sensors

Laser displacement sensors

Contact type displacement sensors

Eddy current type displacement sensors



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# Measurement sensors

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# Measure sensor products



LASER



**HL-C2**  
Ultra High-speed / High-precision  
Laser Displacement Sensor



LASER



**HL-G1**  
Compact Laser Displacement Sensor



LASER



**HG-C**  
Micro Laser Distance Sensor



Multi-Point  
LASER



**HL-D3**  
High Speed, Multi-Point Laser  
Displacement Sensor



LASER



**HL-T1**  
Ultra-compact Laser Collimated  
Beam Sensor



CONTACT



**HG-S**  
Contact-Type  
Digital Displacement Sensor



EDDY CURRENT



**GP-X**  
High Speed / High Accuracy  
Eddy Current Type  
Digital Displacement Sensor

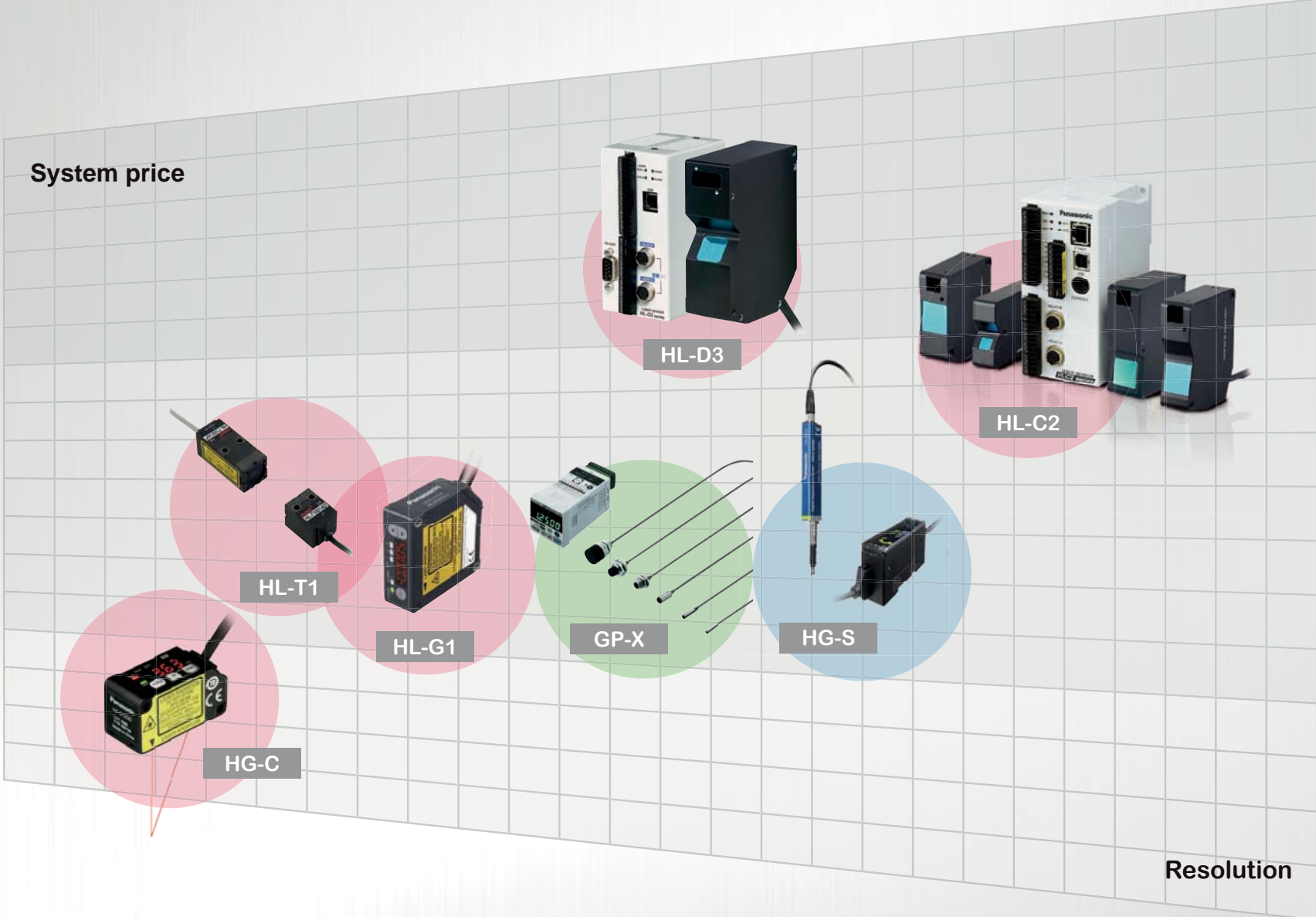
# Specification

Series		Spot size	Resolution	Measurement range	Sampling rate	Features
	HL-C2	Small 20 to 400 $\mu$ m (Line spot type) 700 to 6,500 $\mu$ m	0.01 to 0.2 $\mu$ m	7.2 to 550mm	minimum 10 $\mu$ s	Ultra High-speed • High-precision Laser Displacement Sensor
	HL-G1	Small 100 to 3,500 $\mu$ m	0.5 to 20 $\mu$ m	24.3 to 400mm	minimum 200 $\mu$ s	Compact Laser Displacement Sensor
	HG-C	Small 50 to 500 $\mu$ m	Repeatability 10 to 800 $\mu$ m	25 to 600mm	fixed value 500 $\mu$ s	CMOS type Micro Laser Distance Sensor
	HL-D3	50 $\mu$ m × 15mm	1 $\mu$ m	40 to 60mm	minimum 80 $\mu$ s	High Speed, Multi-Point Laser Displacement Sensor
	HL-T1	-	Repeatability 4 $\mu$ m	-	-	Ultra-compact sensor head A high-functionality intelligent controller
	HG-S	Large	0.1 to 0.5 $\mu$ m	10mm	-	Slim & Robust Sensor Unit Introducing Contact-Type Digital Displacement Sensor Featuring optical absolute method in the slim and strong unit body
	GP-X	Large	0.32 to 20 $\mu$ m	0 to 10mm	fixed value 25 $\mu$ s	High Speed High Accuracy Eddy Current Type Digital Displacement Sensor

The resolution changes depend on setting of the sampling cycle and the response frequency. And the accuracy also related to the ambient temperature and lineality.

Please consult with our sales when selecting the measurement sensor products.

# Product positioning

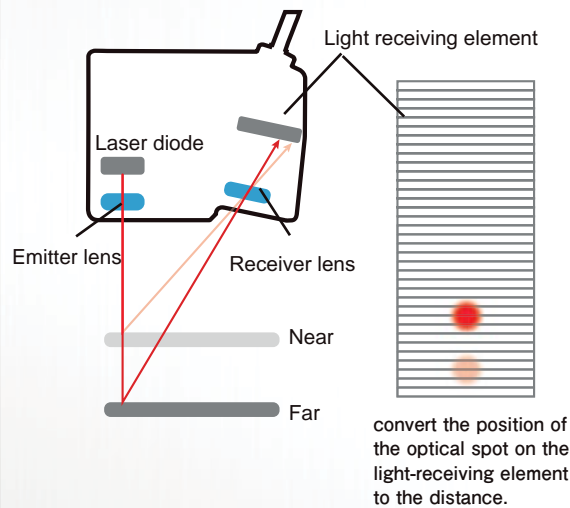


# Principles

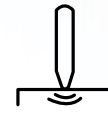


## Laser displacement sensors

Measures the distance to the object, by using the triangulation principal. (Measures displacement or thickness)

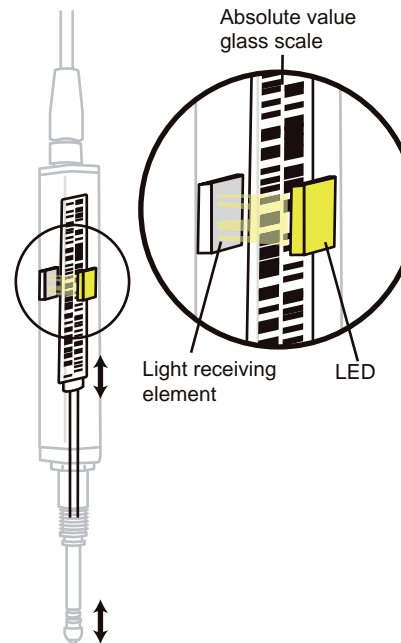


- Long sensing distance
- Measurement by small beam spot
- High speed measurement
- Multi-point type allow the profile measurement
- Measurement will be influenced by the environment



## Contact-Type displacement sensors

Measures the distance by contacting the object. As the sensor pushed in, the glass scale inside moves and displacement can be read distance from the glass slit.

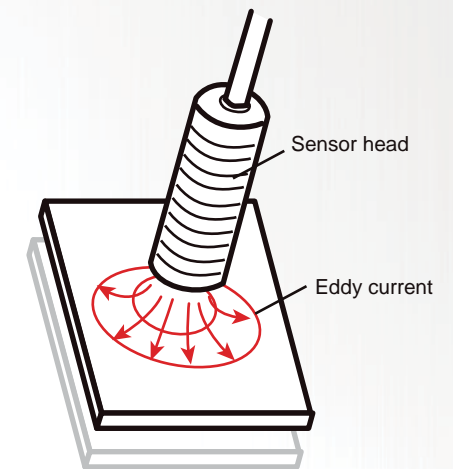


- High resolution
- Not affected by the surface condition
- No influence from the environmental condition
- The risk of causing damage by the contacting
- Longer tact time



## Eddy current type displacement sensors

Measures the distance by using impedance change from electromagnetic induction.



- No influence from the environmental condition
- Suitable for the high-speed moving application
- High resolution
- Contactless and no damage
- Short measurement distance

# Choosing the right measurement sensor

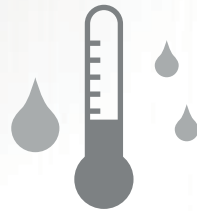
For choosing your right measurement sensor, you need to consider several conditions.

## Measurement object



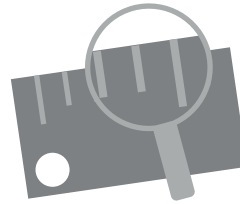
Choose the type of measurement according to material, size or surface state.

## Ambient environment



Choose the sensor considering the surrounding oil mist or temperature.

## Precision



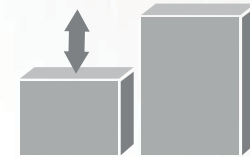
Choose the sensor by the required accuracy.

## Cycle time










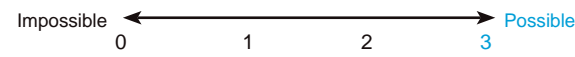
Choose the sensor by required tact time.

## Range



Narrow sensor candidates by considering the distance from the object or required measurement range.

Series		Method	Metal		Plastic			Glass		Low reflective object	
			Metal (Mirror surface)	Metal (Hairline finished)	Plastics (Transparent)	Plastics (Half transparent)	Opaque plastics	Glass (Transparent)	Glass (Half transparent)	Black rubber	Soft body objects
	HL-C2	Distance (1 head)	3	3	3	1 <sup>*A</sup>	3	2	2	2	1
		Thickness (2 heads)	Specular reflective	Diffuse reflective	Specular reflective	Specular reflective	Diffuse reflective	Specular reflective	Diffuse reflective	Diffuse reflective	Diffuse reflective
	HL-G1	Distance (1 head)	3	3	3	1	3	2	2	2	0
		Thickness (2 heads)	Specular reflective	Diffuse reflective	0	0		Diffuse reflective	0		
	HG-C	Distance (1 head)	1	3	0	1 <sup>*A</sup>	3	0	2	2	0
		Thickness (2 heads)							0		
	HL-D3	Distance (1 head)	2 <sup>*A</sup>	3	1 <sup>*A</sup>	1	3	1 <sup>*A</sup>	2	1	0
		Thickness (1 head)									
	HL-T1	Distance (1 head)	3	3	0	1	3	0	1	3	1
		Thickness (1 head)	1	1			1			1	
	HG-S	Distance (1 head)	3	3	3	3	3	2	3	1	0
		Thickness (2 heads)									
	GP-X	Distance (1 head)	3	3	0	0	0	0	0	0	0
		Thickness (2 heads)									



\*A: For the glossy surface, measurable with Specular reflective



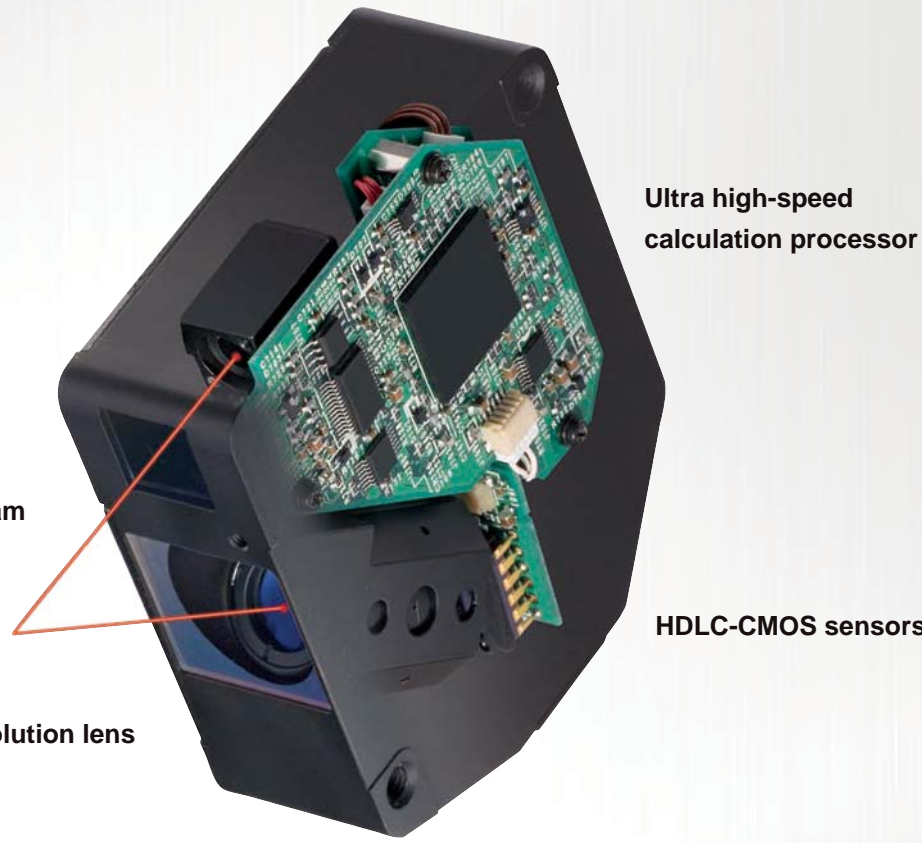


# HL-C2

Ultra High-speed / High-precision  
Laser Displacement Sensor



Sampling rate	Linearity	Resolution
<b>100 kHz</b>	<b>±0.02%</b>	<b>0.01 μm</b>



Micro Spot Gaussian Beam

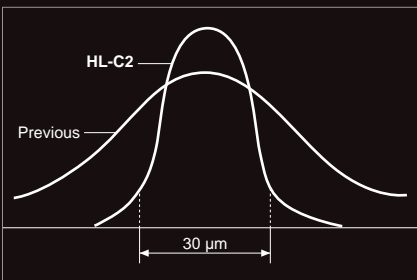
High-resolution lens

Ultra high-speed  
calculation processor

HDLC-CMOS sensors

## Micro Spot Gaussian Beam

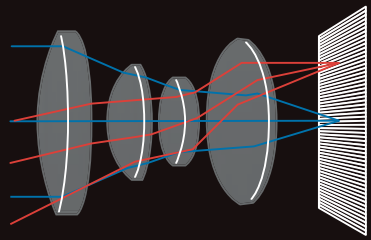
Exclusive optical equipment and diaphragm structure sustain laser beam of high quality at a radiant density that is close to ideal in the Gaussian distribution.



Image

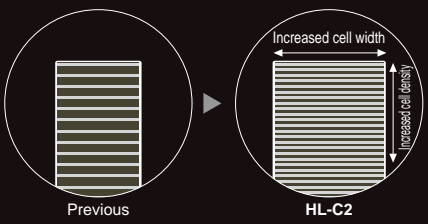
## High-resolution lens

The light-receiving part can create images at a minimum point from light received from a variety of different angles to produce images with even greater precision.



## HDLC-CMOS sensors

High density light-receiving cells and a processing speed which is close to maximum limits result in high resolutions and high speeds which exceed all expectations for laser displacement sensors.



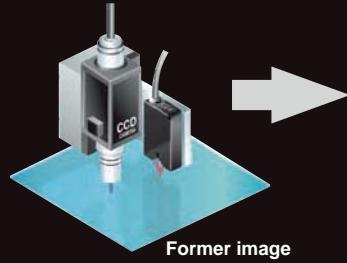
## Ultra high-speed calculation processor

All signals are digitalized by a high speed processor while achieving high precision and high speed with its exclusive algorithm.



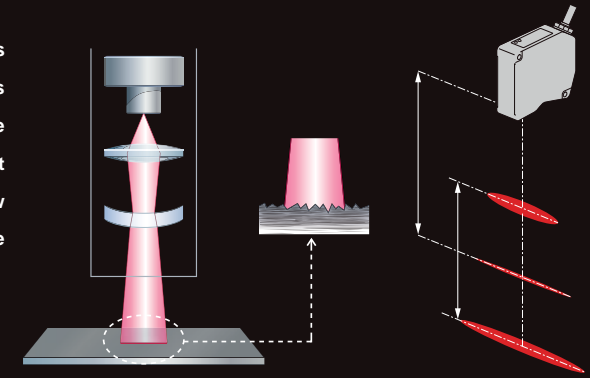
Separate type

Realize the stable measurement by coaxially align the drop from nozzle and measurement point.



Linear beam spot type (-MK)

Even the object which looks flat has some roughness at the surface. This roughness cause the variation with the measurement result. By using line-spot type, averaging the influence and allow the stable measurement even on the rough surface.



Head lineup

	HL-C201F(-MK)	HL-C201A-SP2(M)	HL-C201A-SP3(M)	HL-C203F(-MK)	HL-C205B(-MK) HL-C205C(-MK)	HL-C208B(-MK) HL-C208C(-MK)	HL-C211F(-MK) HL-C211F5(-MK)	HL-C235BE(-MK) HL-C235CE(-MK)	HL-C235CE(-MK)	HL-C235CE(-MK)	HL-C235CE(-MK)	HL-C235CE-W(-MK)	
Measurement center distance	10mm	8mm	15mm	30mm	50mm	85mm	110mm	350mm	350mm	350mm	350mm	350mm	
Measuring range	±1mm	±0.8mm	±1mm	±5mm	±5mm	±20mm	±15mm	±50mm	±50mm	±50mm	±50mm	±200mm	
Resolution	0.01 μm	0.01 μm	0.01 μm	0.025 μm	0.05 μm	0.15 μm	0.1 μm	0.5 μm	0.5 μm	0.5 μm	0.5 μm	0.5 μm	
Beam size	φ20 μm	φ20 μm	φ30 μm	φ30 μm	φ70 μm	φ100 μm	φ80 μm	φ250 μm	φ250 μm	φ250 μm	φ250 μm	φ400 μm	



# HL-C2

Ultra High-speed / High-precision  
Laser Displacement Sensor

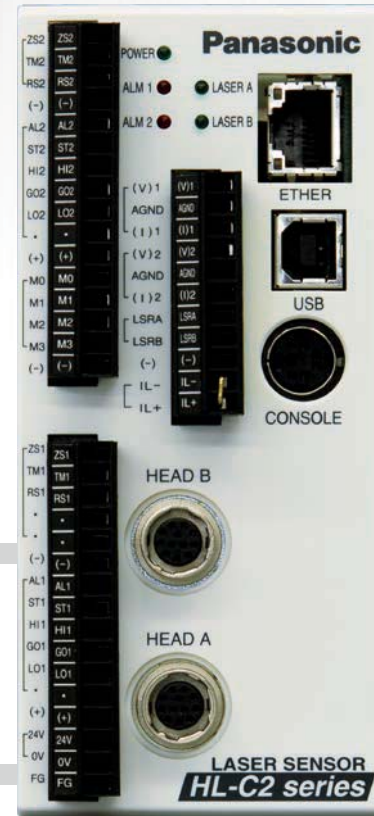


Ethernet type  
HL-C21C(-P)



RS-232C type  
HL-C2C(-P)

Controller  
HL-C21C(-P)  
HL-C2C(-P)



Console connection cable  
HL-C2GT-C3



Programmable display  
GT12

USB 2.0



PC

Analog voltage /  
current output



Data Monitoring device

Ethernet or RS-232C  
(by model selection)



PLC

I/O

Devices  
Relays, Switches

## 2 heads with 1 controller

Calculation function is implemented to the controller.

This function allow output of the calculation result from the thickness measurement and 2-point gap measurement directly.



(Typical examples of the calculation)

A+B

-(A+B)

A-B

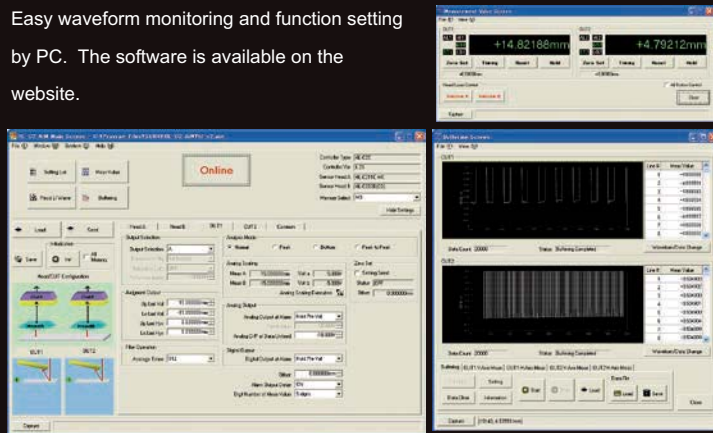
B-A

**Easy operation**

Combining a software tool (Intelligent Monitor HL-C2AiM or Collecting data HL-C2AiG) or Programmable Display GT12, it shows not only measurement results but also received light waveform.

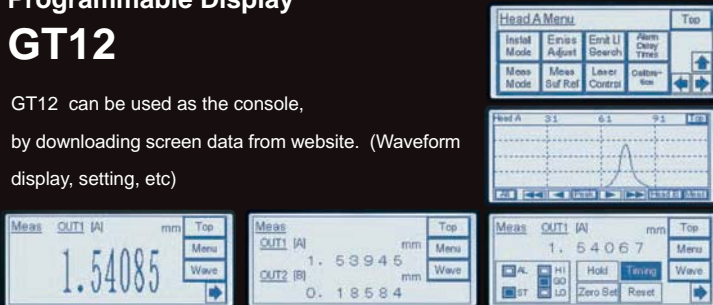
**Setting software HL-C2AiM**

Easy waveform monitoring and function setting by PC. The software is available on the website.

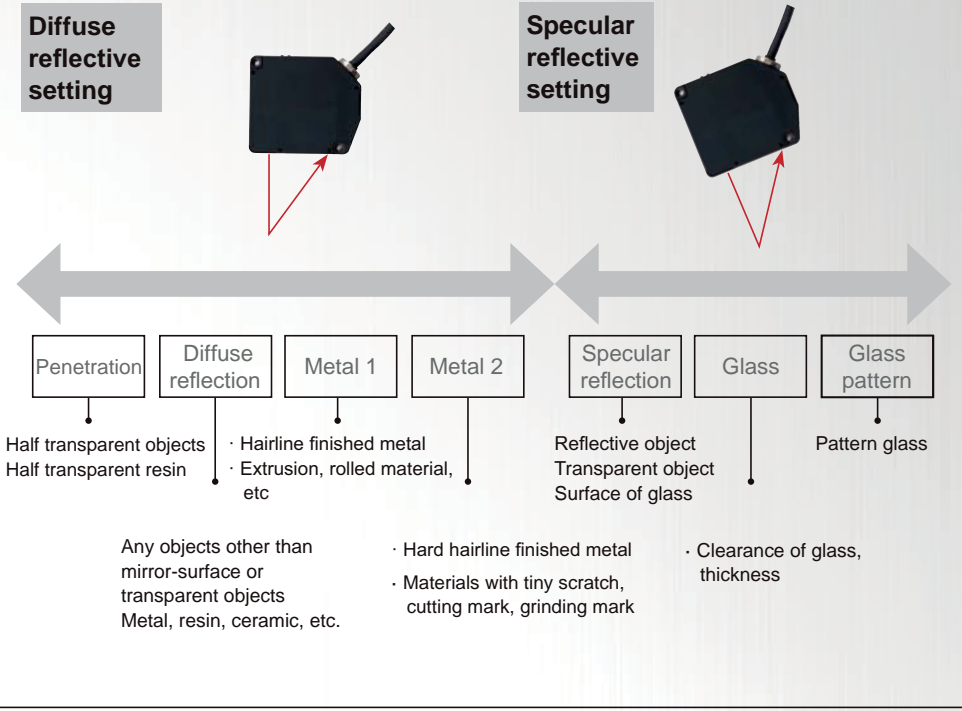


**Programmable Display GT12**

GT12 can be used as the console, by downloading screen data from website. (Waveform display, setting, etc)

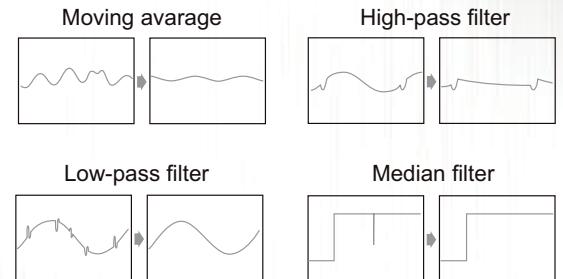


Adjusting the setting, varieties of objects can be measured.

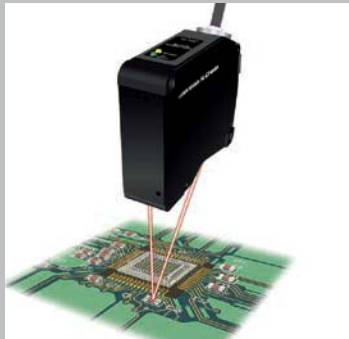


**Various filter functions**

By using suitable filters, customer can realize the high precision measurement.



# Applications



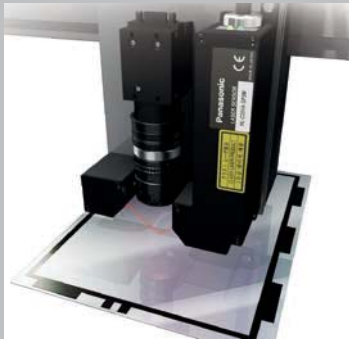
Measurement of the heights of chip parts



Measurement of HDD surface variations



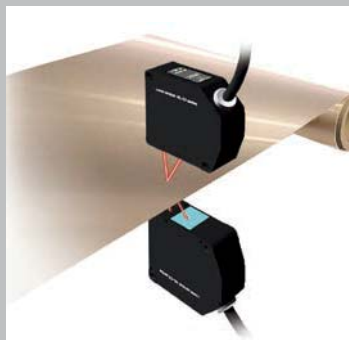
Detection of deformed narrow pitch connector leg pins



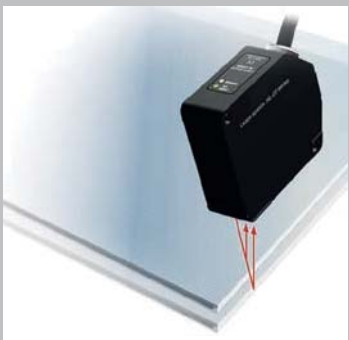
Controlling the camera focus



Measurement of disk brake thickness



Measurement of the thickness of copper clad laminate



Gap measurement between glass and bottom layer



Controlling the nozzle height of a dispenser

# HL-G1

Compact Laser Displacement Sensor

High resolution and Fast response

Resolution    Sampling rate  
**0.5 $\mu$ m**    **200 $\mu$ s**



## Timing input and multi input

In addition to timing input select the desired input according to your application.

- Zero set on/off
- Laser control
- Reset
- Teaching
- Memory switching
- Saving

## Featuring 3 digital and one analog output

- HI/GO/LOW judgment output or Alarm output
- Analog output: current and voltage modes

## Compact size with the built-in controller and digital output

As a self contained sensor, the HL-G1 series offers a space saving configuration by removing the need for an external controller.



## IP67 dust- and water-proof protective enclosure

Exclusive optical equipment and diaphragm structure sustain laser beam of high quality at a radiant density that is close to ideal in the Gaussian distribution.

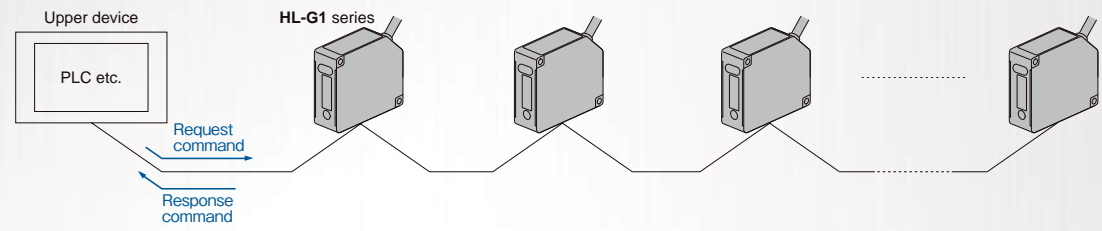


# High functionality type

## Connect to upper devices of RS-422/485.

The HL-G1 can be connected to upper devices of RS-422/485.

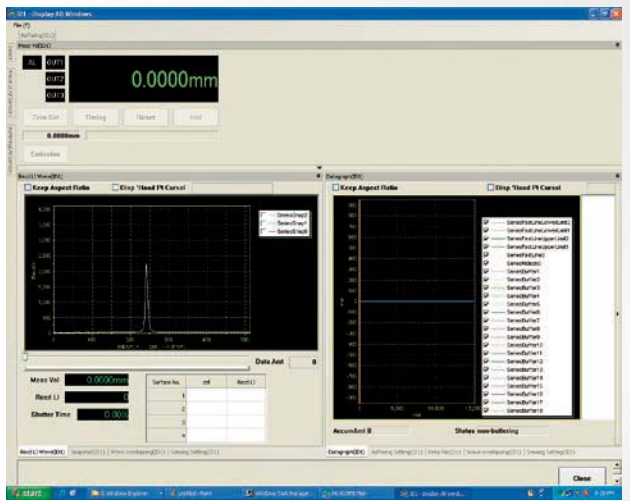
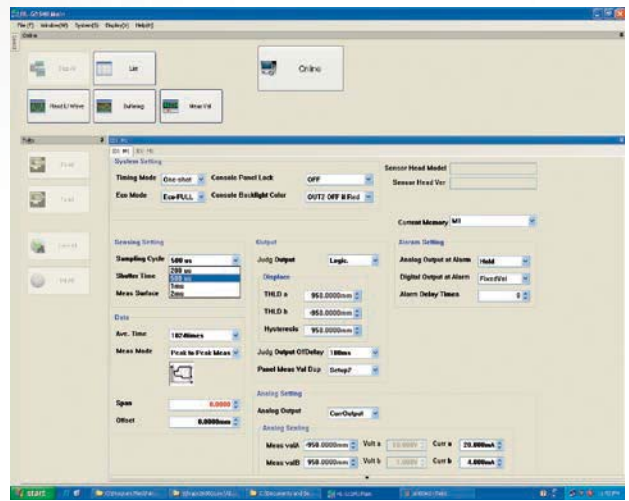
When upper device sends the request command, the HL-G1 series sends the response command.



## Software tool for sensor configuration and evaluation

In addition to configuring up to 16 sensors at once, this free tool makes it easy to gather data needed for analysis, including received light waveform monitoring and data buffering. The interface language can be selected at the time of installation.

- Data buffering
- Received light waveform display
- Measured value display



## HMI screen for the HL-G1 series

The GT02 / GT12 HMI operator panel can be used in combination with the HL-G1 to allow easy confirmation of sensor status and configuration of sensor settings from a remote location.

Japanese, English, Chinese, and Korean are supported.



Diffuse reflective model

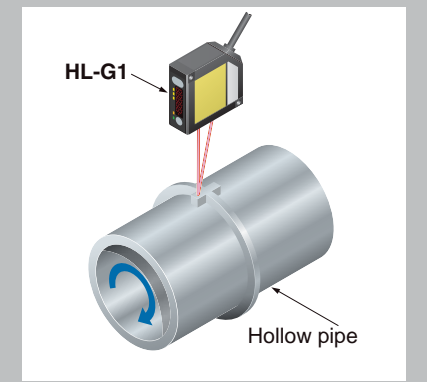
Specular reflective model



	Diffuse	Specular	Diffuse	Specular	Diffuse	Specular	Diffuse	Diffuse
								
	HL-G103□	HL-G103A□	HL-G105□	HL-G105A□	HL-G108□	HL-G108A□	HL-G112□	HL-G125□
Measurement center distance	<b>30mm</b>	<b>26.3mm</b>	<b>50mm</b>	<b>47.3mm</b>	<b>85mm</b>	<b>82.9mm</b>	<b>120mm</b>	<b>250mm</b>
Measuring range	<b>±4mm</b>	<b>±2mm</b>	<b>±10mm</b>	<b>±5mm</b>	<b>±20mm</b>	<b>±10mm</b>	<b>±60mm</b>	<b>±150mm</b>
Resolution	<b>0.5μm</b>	<b>0.5μm</b>	<b>1.5μm</b>	<b>1.5μm</b>	<b>2.5μm</b>	<b>2.5μm</b>	<b>8μm</b>	<b>20μm</b>
Beam size	<b>φ0.1mm</b>	<b>φ0.1mm</b>	<b>φ0.5x1mm</b>	<b>φ0.1mm</b>	<b>0.75x1.25mm</b>	<b>φ0.2mm</b>	<b>1.0x1.5mm</b>	<b>1.75x3.5mm</b>



### Applications




HL-G1

Hollow pipe

Control of hollow pipe positioning

The diagram shows an HL-G1 sensor mounted above a hollow pipe. Two red laser lines project from the sensor onto the top surface of the pipe. A blue arrow on the pipe indicates its rotation.



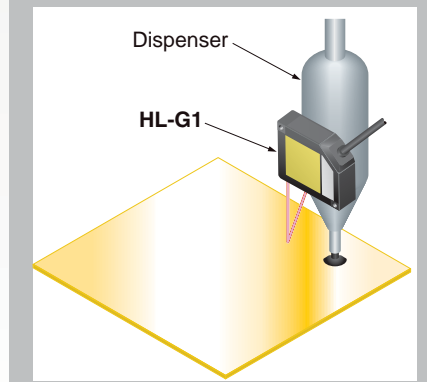
Detecting rotating direction of fan

The diagram shows an HL-G1 sensor positioned above a fan. Two red laser lines project from the sensor onto the fan's blades.



Positioning of wafer

The diagram shows an HL-G1 sensor positioned above a circular wafer. Two red laser lines project from the sensor onto the wafer's surface.



Dispenser

HL-G1

Controlling the height of a dispenser nozzle

The diagram shows an HL-G1 sensor positioned above a dispenser nozzle. Two red laser lines project from the sensor onto the nozzle's tip. A yellow square highlights the area where the nozzle is positioned.



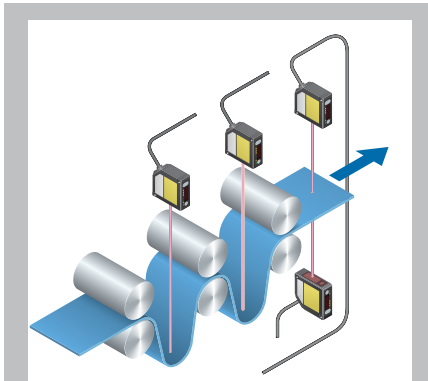
Inspecting processed food quantities

The diagram shows an HL-G1 sensor positioned above a conveyor belt with red food items. Two red laser lines project from the sensor onto the items.



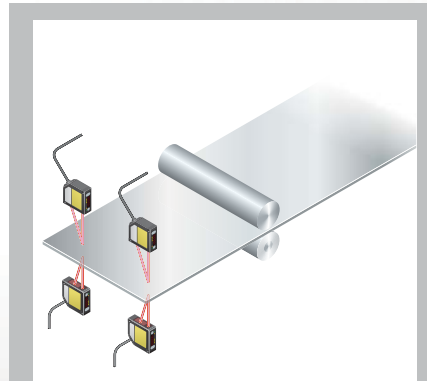
Detection of aluminum wheel grooves

The diagram shows an HL-G1 sensor positioned above an aluminum wheel. Two red laser lines project from the sensor onto the wheel's grooves.



Testing sheet slack

The diagram shows three HL-G1 sensors positioned above a blue sheet of material. Two red laser lines from each sensor project onto the sheet. A blue arrow indicates the sheet's movement.



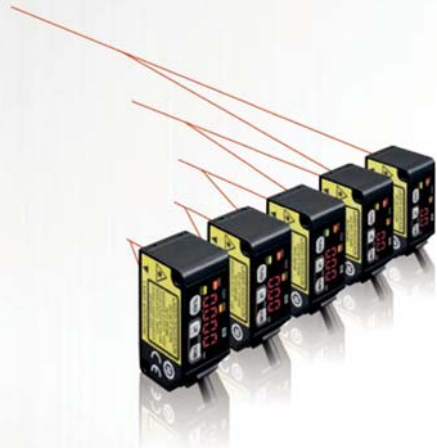
Measuring the thickness of a steel plate

The diagram shows four HL-G1 sensors positioned around a steel plate. Two red laser lines from each sensor project onto the plate's surface.

# HG-C

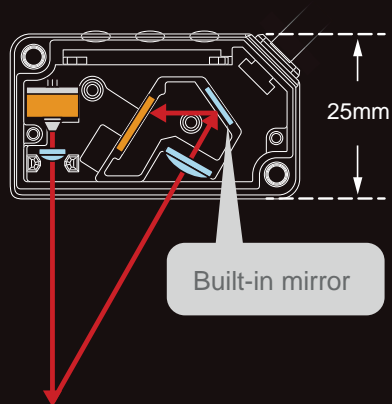
Micro Laser Distance Sensor

Repeatability    Linearity    Response time  
**10 $\mu$ m**     **$\pm 0.1\%$  F.S.**    **1.5ms**



## A new optical system with a built-in mirror

The HG-C series sensors incorporating a new optical system with a built-in mirror provides smaller sensor depth as well as higher measurement accuracy equivalent to displacement sensors.

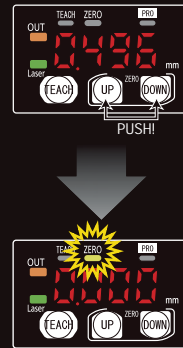


## Standard equipped analog output

Analog output is provided in addition to control output. It can be used as a simple measurement sensor.  
Analog voltage output range: 0 to 5 V  
Analog current output range: 4 to 20mA

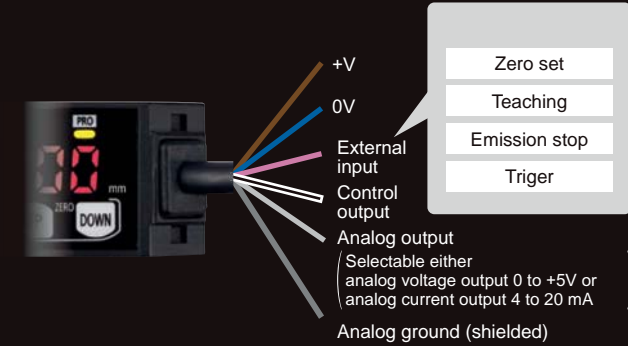
## Zero set function

The zero point can be set at a desired value. It is useful when measuring steps or tolerance with reference to the height of a sensing object.



## External input setting function

One of four functions, "zero setting function," "teaching function," "emission stopping function" and "trigger function" can be assigned to an external input line.



	HG-C1030□	HG-C1050□	HG-C1100□	HG-C1200□	HG-C1400□
Measurement center distance	30mm	50mm	100mm	200mm	400mm
Measuring range	±5mm	±15mm	±35mm	±80mm	±200mm
Repeatability	10μm	30μm	70μm	200μm	300μm (200 to 400 mm) 800μm (400 to 600 mm)
Beam diameter	φ50μm	φ70μm	φ120μm	φ300μm	φ500μm

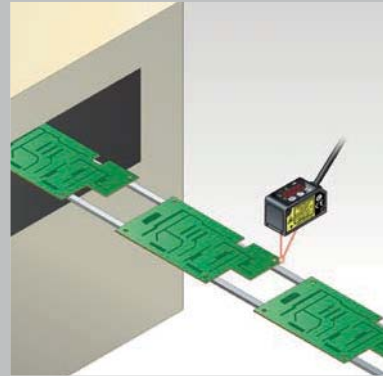
## Applications



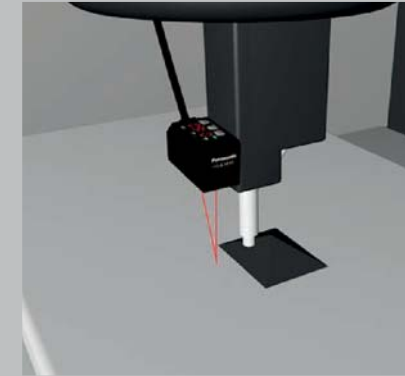
Controlling the mounter head height



Detecting on-vehicle seats



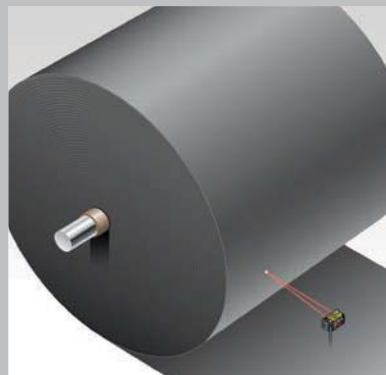
Detecting warpage of a circuit board



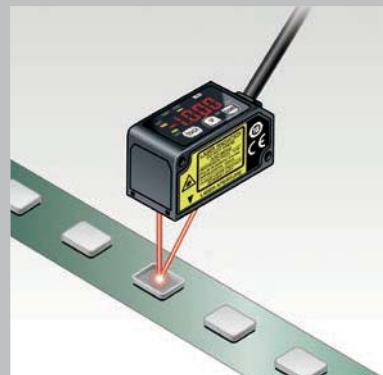
Measuring the distance of 3D printer injector and part



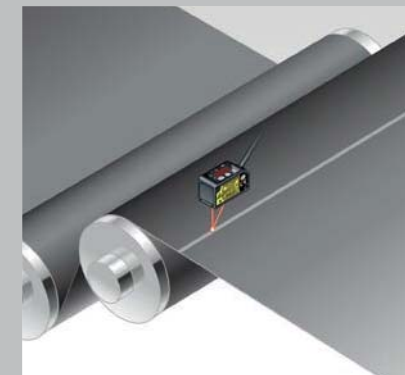
Checking of correct pins alignment of connector



Measurement of a remaining functional sheet



Judging front or back of cover of electric parts



Detecting a seam (overlap) of functional sheet

# HL-D3

High Speed, Multi-Point Laser Displacement Sensor

## High Speed Multi-point Sensing

Resolution

Z axis

**1**  $\mu\text{m}$

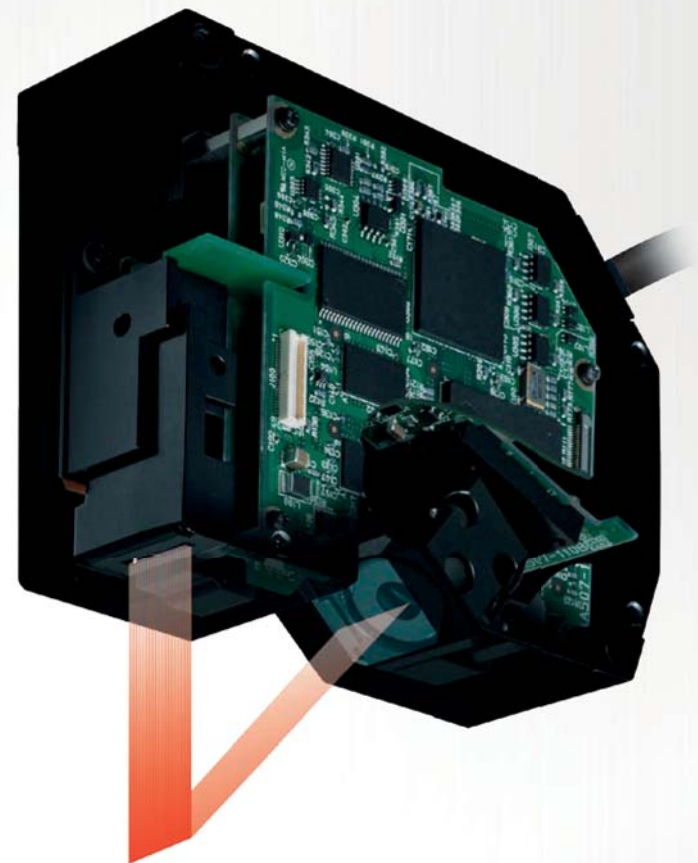
Sampling rate

**80**  $\mu\text{s}$

Measurement range of width (X axis)

**12.5** mm

\*measurement center



## Parallel beam

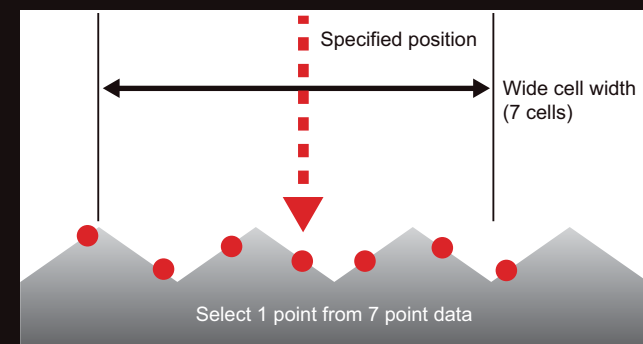
HL-D3 adopts parallel beam made possible by the latest optical system. The reduced area of shadow that appears when light is emitted on the target object made it possible to accurately sense the shape of the object.



## Wide-cell function

When the surface condition is rough, such as with cut metal, sensing of a single point will result in errors due to the uneven surface.

The wide-cell function expands the sensing points for the light receiving side and obtains the mean value (or maximum or minimum value, depending on the setting) to improve the stability of the measurements.



## Multiple Shape Calculation Functions

The HL-D3 series calculates the shapes, including the height difference, width, and cross-sectional area, from the shape waveform based on the received light. At the same time, the displacement sensor uses these calculation results to instantaneously make Hi / Go / Lo judgments based on the present upper and lower limits.

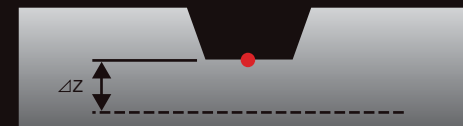
Thanks to the two sets of output, different shape calculations can be performed for each output or two sensor heads can be connected and used to output each judgment results.



## Multiple Shape Calculation Functions

### Height calculation

The height difference between the reference value and measured value is calculated.



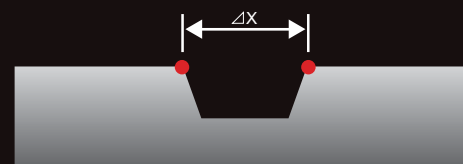
### Step calculation

The height difference is calculated from 2 measured values.



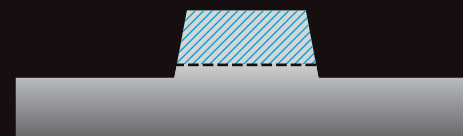
### Width calculation

The width is calculated from 2 measured values.



### Cross-sectional area calculation

HL-D3 calculates the cross-sectional area defined by the reference value.



# Settings & Monitoring Software HL-D3SMI

Conditions and the monitoring of measurements and judgment results can easily be set up by connecting to the HL-D3C controller and a PC pre-installed with HL-D3SMI using USB cables. The shape waveform based on the saved data can be reproduced on screen, which allows for it to be used as an analytical tool.



- Store displacement shape waveform data, calculated measured values, and judgment results on the memory built into the controller during continuous sensing.
- Provides a stereoscopic representation of the shape by a 3D display of stored data.
- Replay the stored data on the buffering screen at a later time, provided that the stored data is saved in the dedicated file format.
- Allow waveform display and analysis by means of spreadsheet software based on the data saved in CSV file format.

	OUT1	OUT2	OUT3	OUT-OUT calc1	OUT-OUT calc2
Value	0.893 mm	4.496 mm	0.256 mm	999.999 mm	999.999 mm

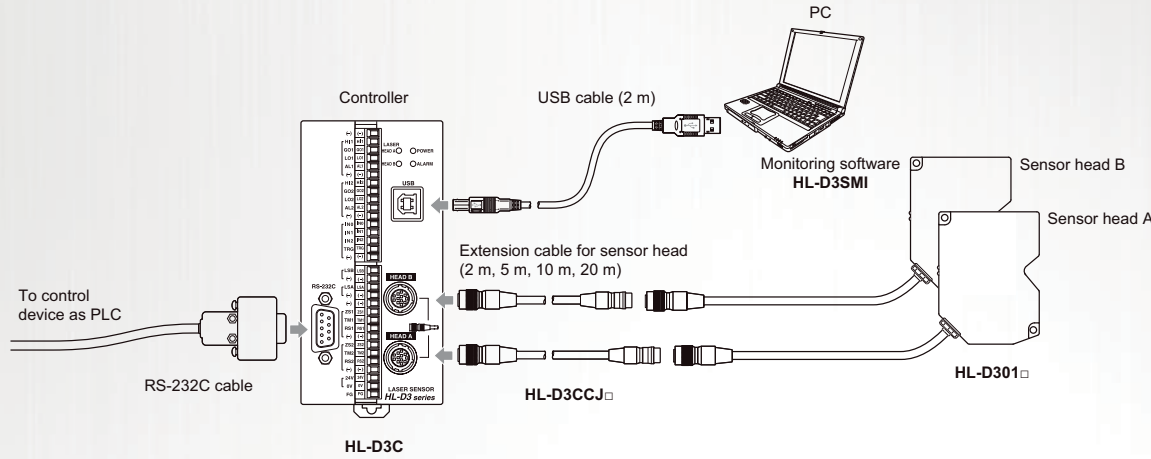
  

	Meas. pos.1	Meas. pos.2	Meas. pos.3	Meas. pos.4	Meas. pos.5
Value	999.999 mm	999.999 mm	999.999 mm	999.999 mm	999.999 mm

Head	No. of accum. pts.	Total time	Status
Head A	325	3.253s	Buffering complete
Head B	0	0us	Buffering complete

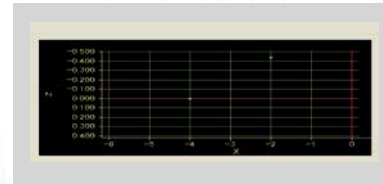
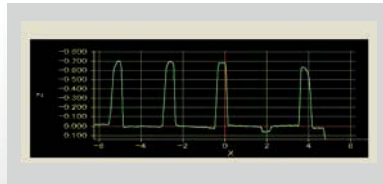
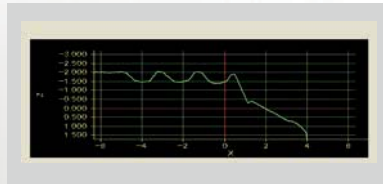
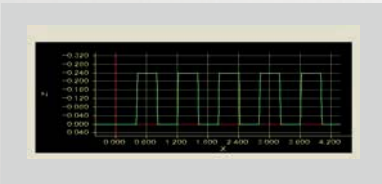
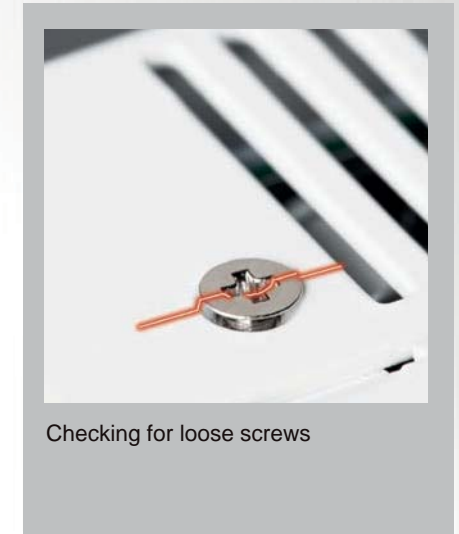
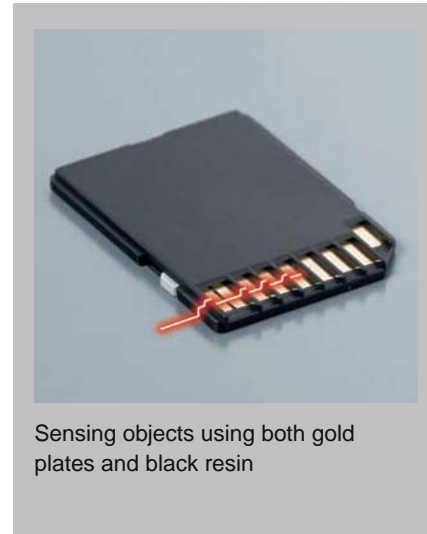
### System configuration



### Line-up

	HL-D301B	HL-D301C
Laser class	Class 2	Class 3R
Measurement center distance	<b>50mm</b>	
Measuring range (Z axis)	<b>±10mm</b>	
Width (X axis)	<b>12.5mm</b>	
Resolution (Z axis)	<b>1µm</b>	

### Applications

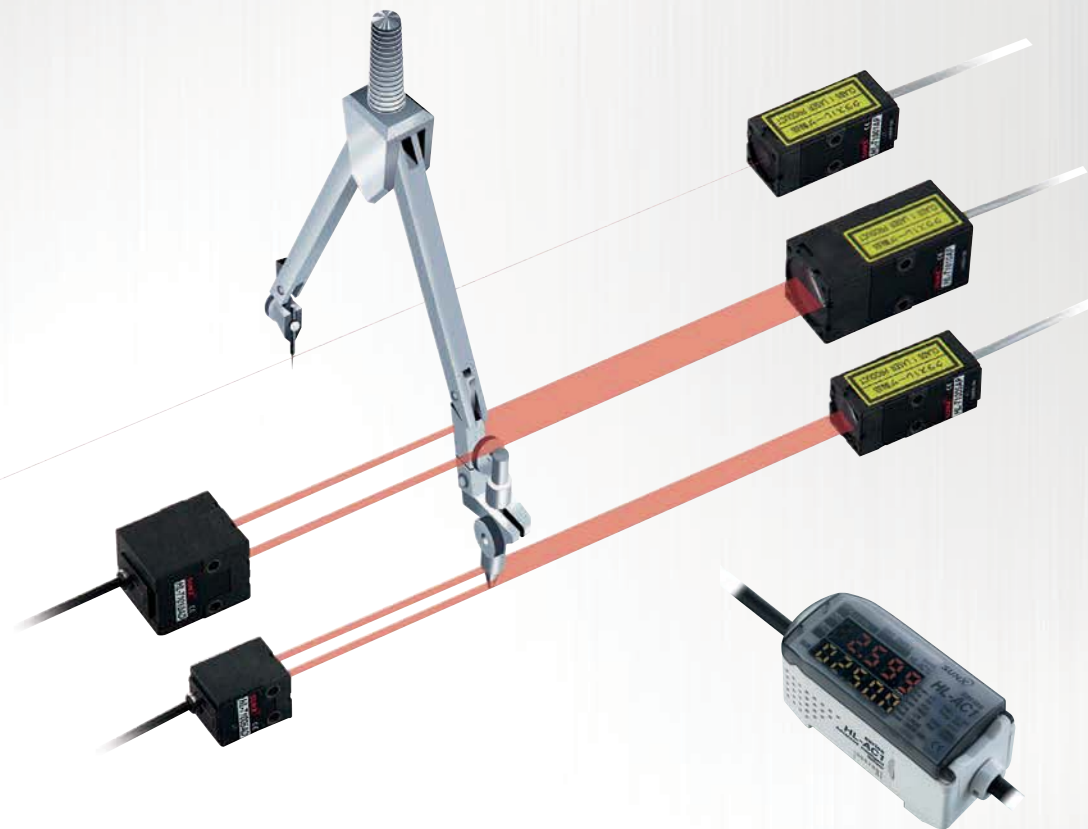




**HL-T1**  
Ultra-compact Laser Collimated Beam Sensor

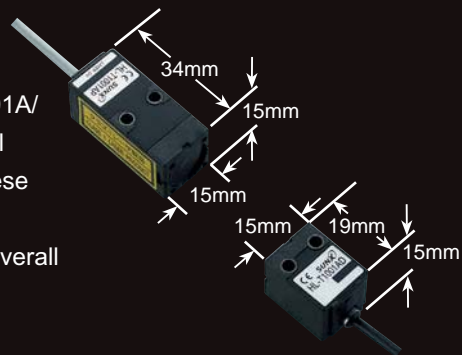
Ultra-compact sensor head  
A high-functionality intelligent controller

Resolution	Minimum sensing object	Sampling rate
<b>4<math>\mu</math>m</b>	<b>8<math>\mu</math>m</b>	<b>150<math>\mu</math>s</b>



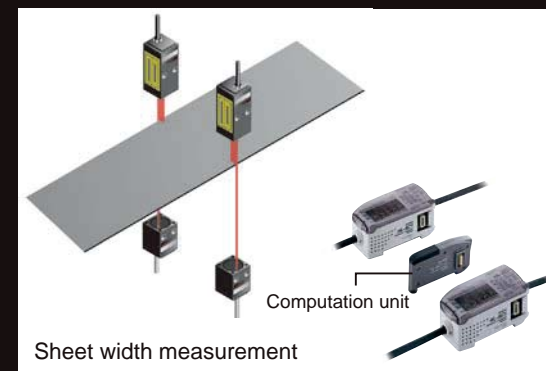
**Small sensor head**

The most compact size (HL-T1001A/ T1005A) and yet the highest level of performance in their class. These sensors require less space for installation and contribute to overall space savings.



**Computations for 2 sensors**

The computation unit (option) just needs to be connected between the two controllers to enable computations (addition and subtraction) to be carried out for two sensors. No digital panel controller is needed either.







## HG-S

Contact-Type Digital Displacement Sensor

### Slim and Robust sensor

Resolution    Indication accuracy

**0.1**  $\mu\text{m}$     **1.0**  $\mu\text{m}$  or less

\*10mm type sensor head

Measurement  
range

**10**mm/**32**mm



### Sensor head

### Slim body

The slim unit body contains plain bearings with 2-point support structure disperses load and achieves superb durability. The sensor head offers long life and reduces maintenance costs dramatically.

### 2-point support structure

Ball-less bearings are installed at the upper and lower sections of the unit. This ensures excellent strength against lateral loads.

### No "value skipping" or "unset zero point"

Displacement is measured by reading a glass scale with a different slit pattern at each reading position using a high-resolution sensor. This eliminates "value skipping" even when measuring at high speed, and there is no concern of "unset zero point".

### Hot-swappable

The sensor head can be changed safely without turning off the controller. This reduces the man-hours required for the change of line setup for processing of different workpieces, thus achieving a significant reduction of setup change time.

## Controller

### Dual display

The 2-line digital display simultaneously shows head measurement (measured value) and judgment value (calculated value).

### Intuitive circle meter

Values between allowable maximum and minimum values are indicated in green. Values outside of the allowable range are indicated in orange. This provides at-a-glance understanding of the margin to the tolerance limits.

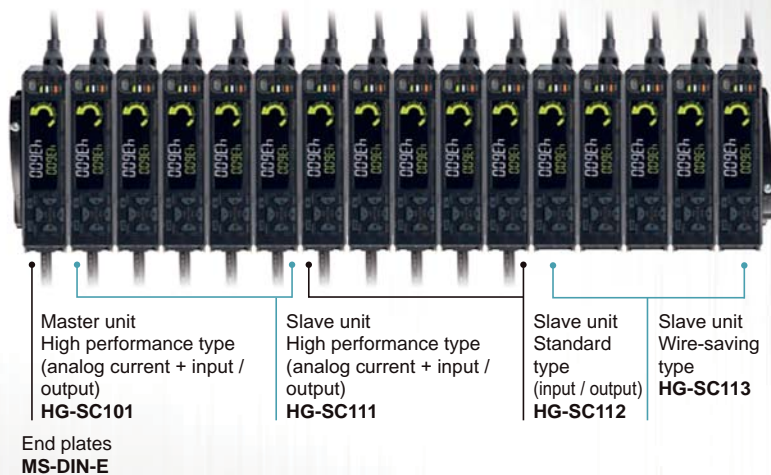


### Connection of up to 15 slave units

One master unit can be connected with up to 15 slave units in any order. This allows easy multi-point calculations.



(Example: Connection of 15 slave units)



\*End plates (optional) must be mounted on both sides of the controller after the connection of slave units.

Sensor head



	HG-S1010	HG-S1010R	HG-S1110	HG-S1110R	HG-S1032
Type	Standard	Low measuring force	High precision Standard	High precision Low measuring force	Standard
Measuring range	10mm	10mm	10mm	10mm	32mm
Resolution	0.5μm	0.5μm	0.1μm	0.1μm	0.5μm

Controller



	HG-SC101	HG-SC111	HG-SC112	HG-SC113
	HG-SC101-P	HG-SC111-P	HG-SC112-P	
	High performance Analog current output		Standard	Wire-saving

## Applications



Screw head height measurement



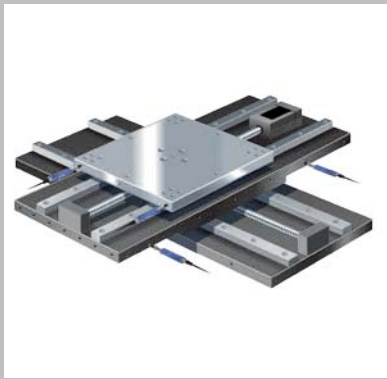
Transmission parts height measurement



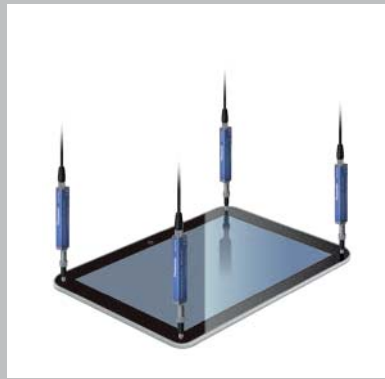
Motor shaft eccentricity measurement



Automotive parts dimension measurement



X-Y stage position measurement



Tablet surface flatness measurement



Resin roller eccentricity measurement



Coupling assembly inspection

# SC-HG1-C / SC-HG1-CEF

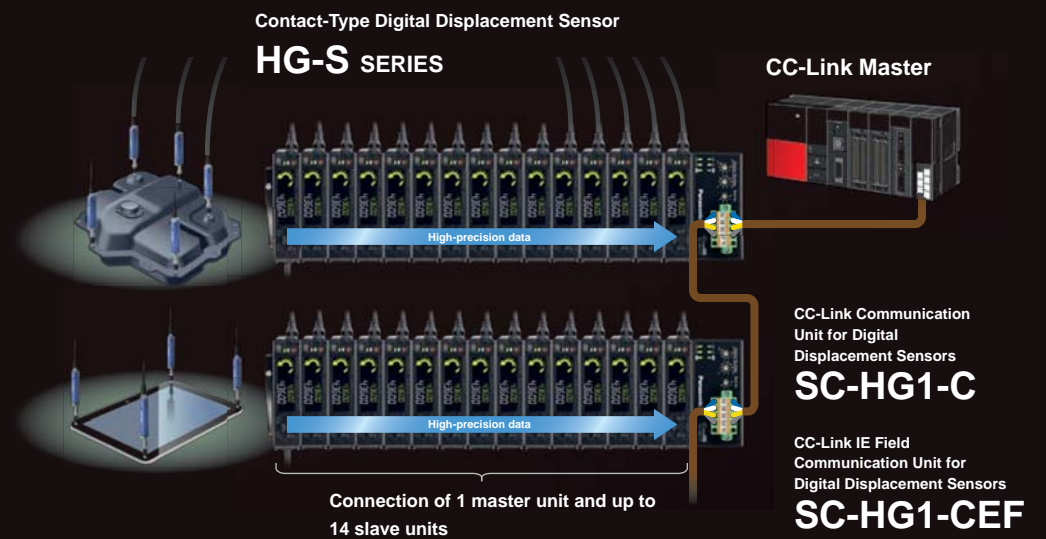
CC-Link / CC-Link IE Field Communication Unit  
for Digital Displacement Sensors



Direct connect to CC-Link master

Program-less transmission of high-precision data

Batch change of internal settings via CC-Link

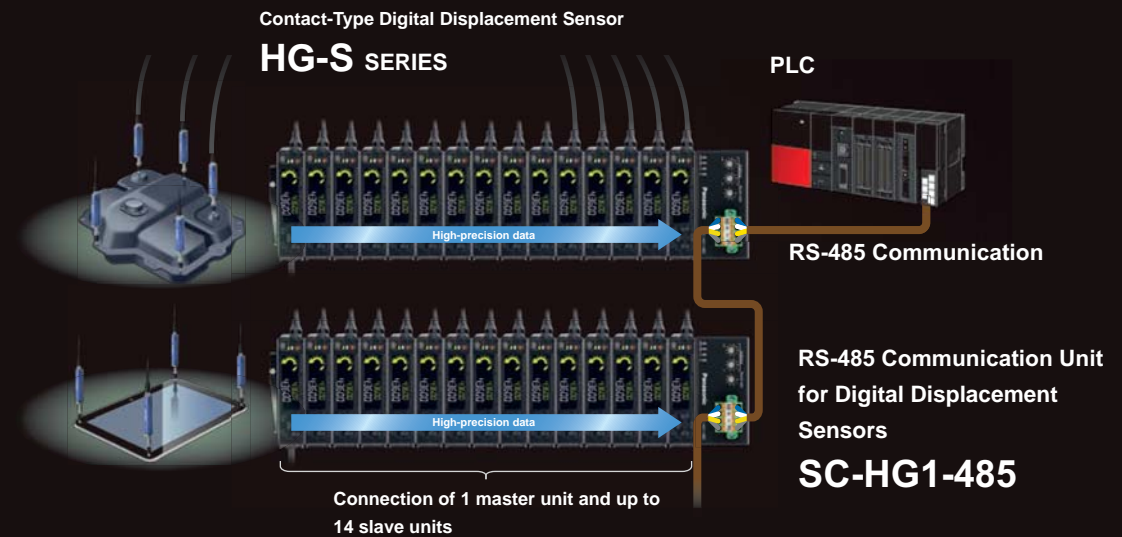


# SC-HG1-485

RS-485 Communication Unit  
for Digital Displacement Sensors



Direct transfer of high-precision measurement values  
Batch change of internal settings via RS-485







## GP-X

High Speed / High Accuracy Eddy Current Type  
Digital Displacement Sensor



High-speed sampling and high resolution.

Sampling rate

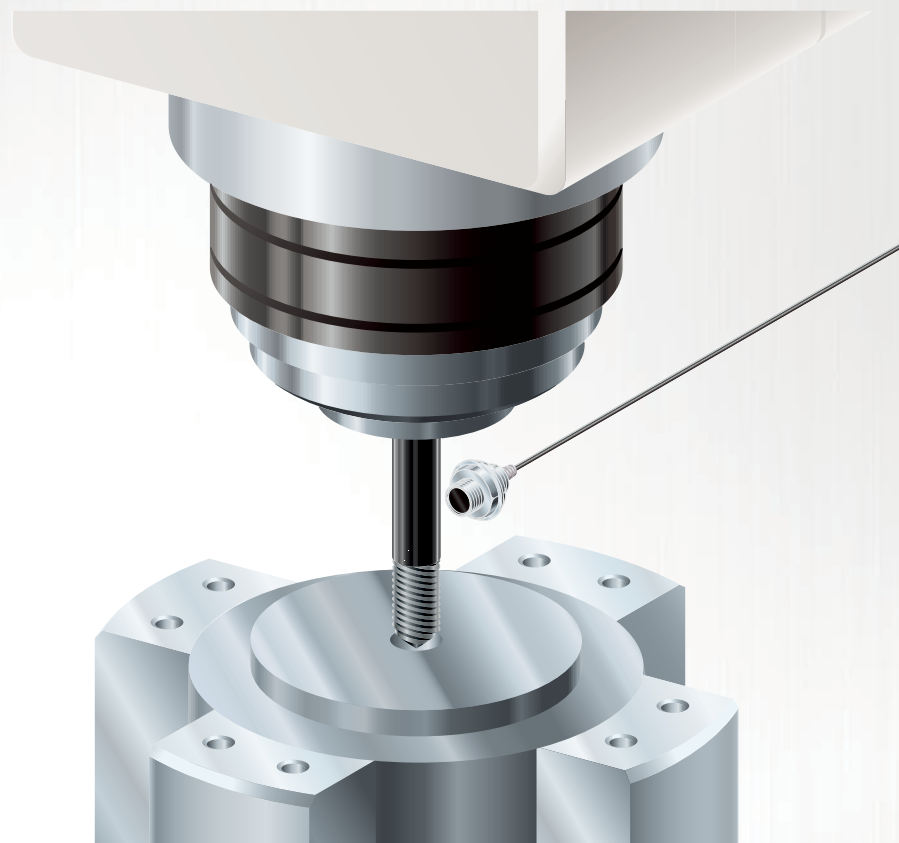
**25 $\mu$ s**

Linearity

**$\pm 0.3\%$  F.S.**

Resolution

**0.32 $\mu$ m**



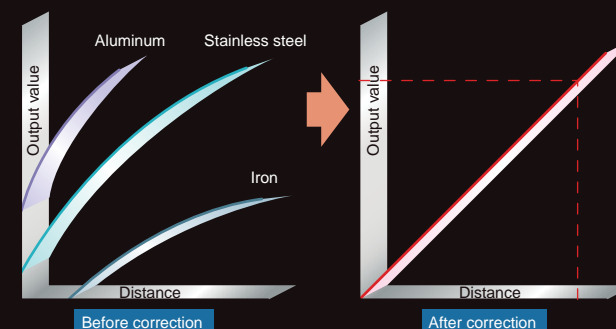
### 0.02 % F.S. resolution for highly accurate measurement

With high resolution, 0.02 % F.S. (Note), they can perform highaccuracy measurements of micro-displacements. (Average number of samples: 64)

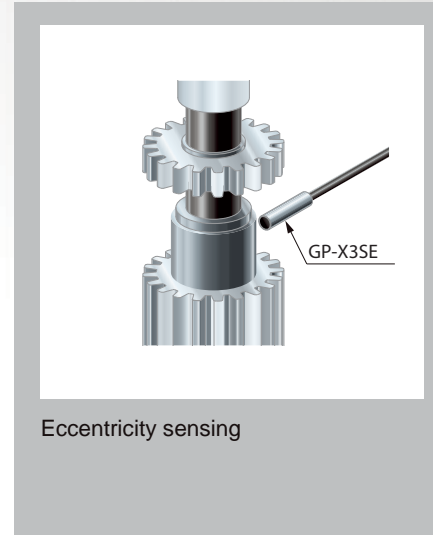
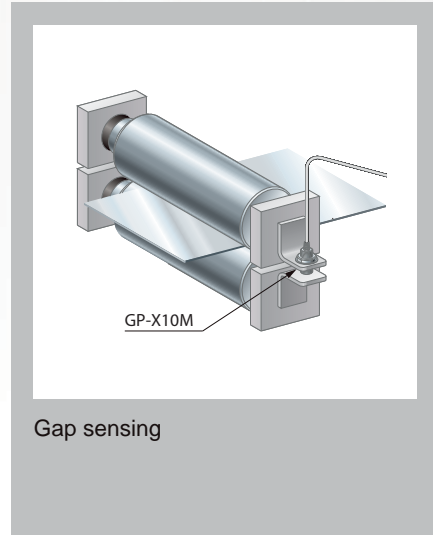
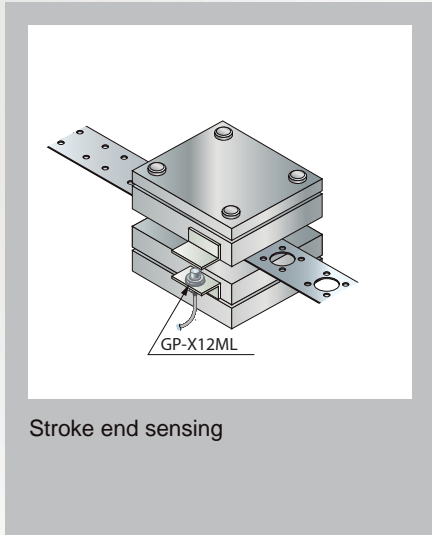
Note: GP-XC3SE and GP-XC5SE Resolution: 0.04 %F.S.

### Optimal correction of the output characteristics

Because they perform with a 0.3 % F.S. linearity, they can be used for sensing stainless steel and iron enabling precise measurements not affected by the work's material. Specifications corresponding to each material (stainless steel, iron, aluminum) has already been inputted in the controller enabling the easy selection of the setting that is most suitable for the particular material used.



## Applications



Type	GP-XC22KL(-P)	GP-XC12ML(-P)	GP-XC10M(-P)	GP-XC8S(-P)	GP-XC5SE(-P)	GP-XC3SE(-P)
Measuring range	10mm	5mm	2mm	2mm	1mm	0.8mm
Appearance	φ22mm	M12	M10	φ8mm	φ5.4mm	φ3.8mm

# Programmable logic controller FP7

FP7 allows building traceability system by the remote monitoring and data logging functions, addition to the equipment control.

Program capacity

**196k** steps

Ultra high speed processing

**11** ns/step

I/O points

**Max. 4096** Points



Add-on cassettes  
Analog input unit  
AFP7FCAD2

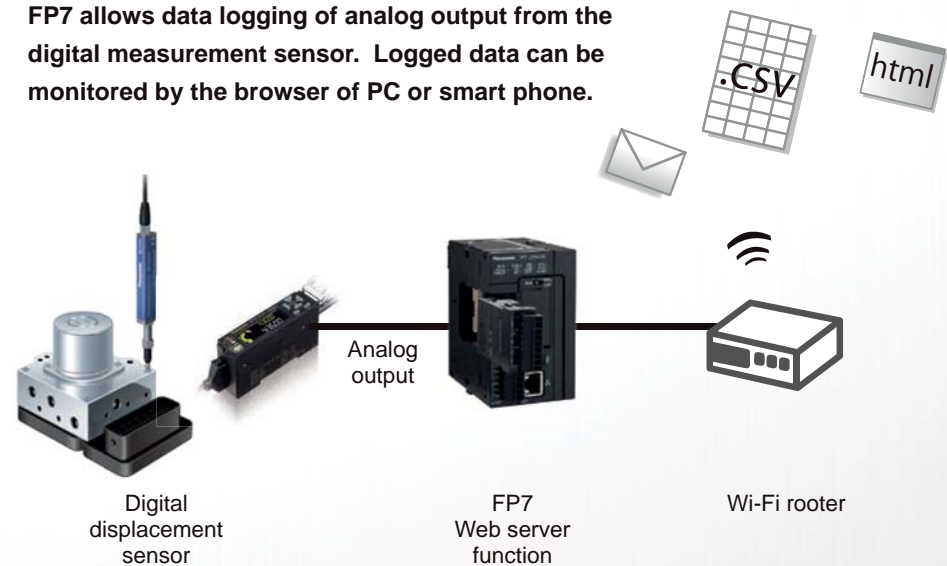
AFP7FCAD2  
2-channel analog input 0–10V/0–5V/0–20mA, resolution  
12 bit, conversion speed 1ms/channel (non-insulated)



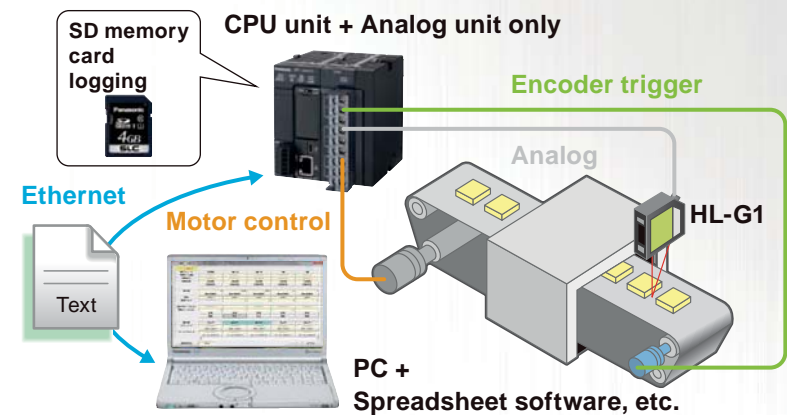
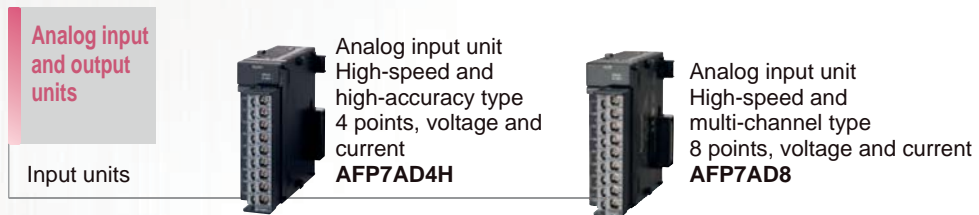
Programmable  
controller  
FP7



FP7 allows data logging of analog output from the digital measurement sensor. Logged data can be monitored by the browser of PC or smart phone.



# Programmable logic controller FP7



# Programmable logic controller

New standard for compact PLCs

## FP0R



Program capacity

**32k** steps

Ultra high speed processing

**80** ns/step

I/O points

**Max. 128** Points

Powerful compact PLC

## FPΣ



Program capacity

**32k** steps

High speed processing

**320** ns/step

I/O points

**Max. 384** Points



Analog Input Unit  
Input: 4 channels  
**AFP0RAD4**



Analog Input Unit  
Input: 8 channels  
**AFP0RAD8**



Analog I/O Unit  
Input: 2 channels / Output: 1 channel  
**AFP0RA21**



Analog I/O Unit  
Input: 4 channels / Output: 2 channels  
**AFP0RA42**



**FP0R**  
Analog Unit



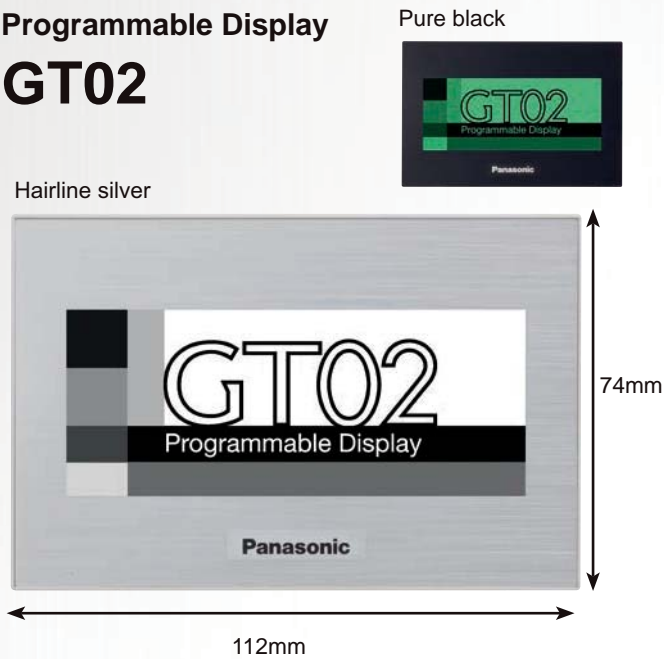
**FP0R**



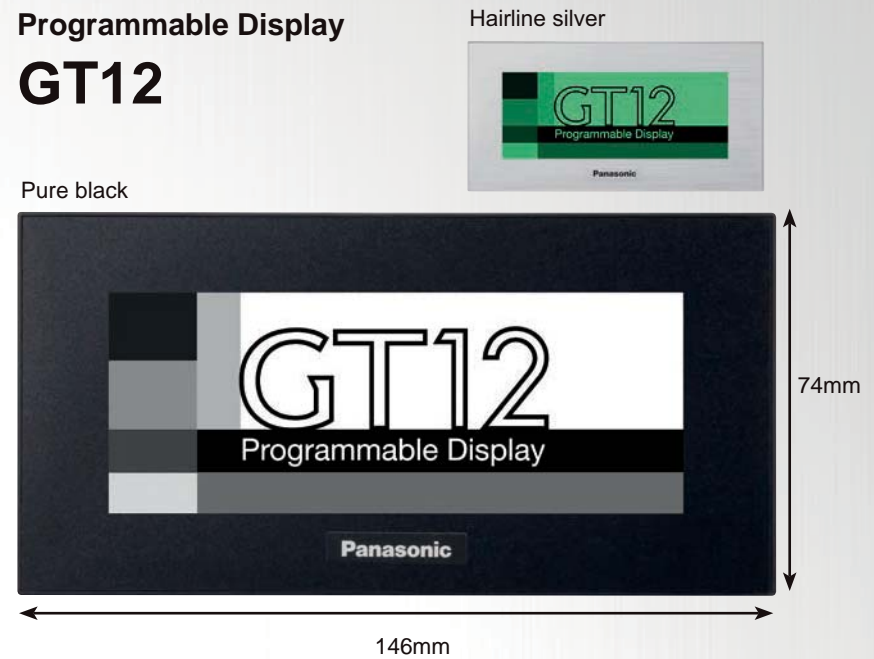
**FPΣ**

# Consoles for measurement sensors

## Programmable Display GT02



## Programmable Display GT12



### GT02 / GT12 Bright three-color LED background

M type

White

Pink

Red

G type

Green

Orange

Red

Ultra High-speed / High-precision  
Laser Displacement Sensor  
HL-C2



**GT12 Selection 4 models**

(RS232C, No SD card slot)

Compact  
Laser displacement Sensor  
HL-G1



**GT02 Selection 4 models**

(24V, RS485, No SD card slot)

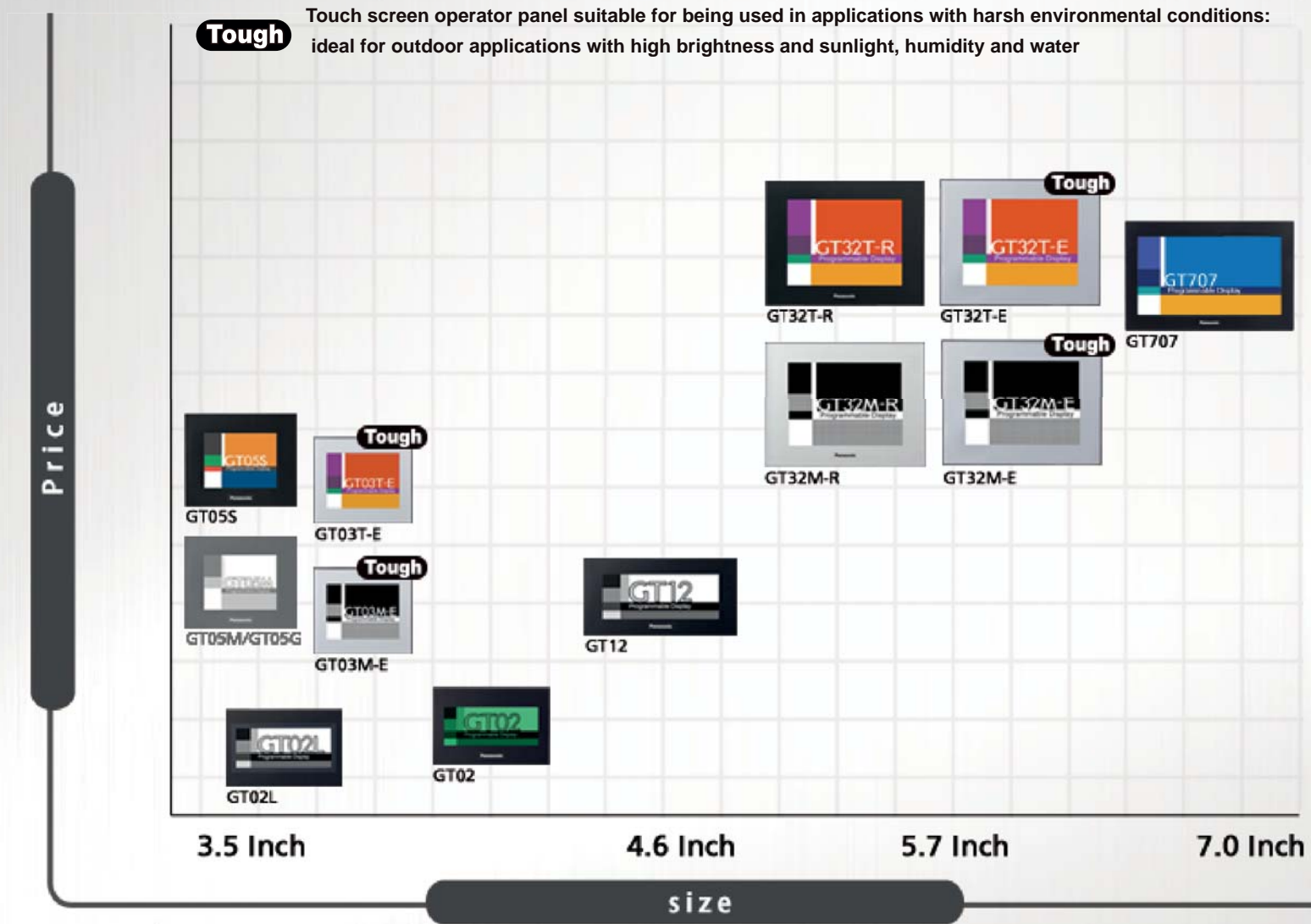
**GT12 Selection 8 models**

(RS485, With/ without SD card slot)

\*Not using SD card for console purpose)

# Human Machine Interface

## GT series



## Global Network

Please Contact our Global Sales Companies in:

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